

Supplementary File 1: Estimation algorithm and algorithm for the null model.

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495 **A Estimation algorithm**

496 Here we present the algorithm used for fitting the quantile VMICM model.

497 *Step 1 & 2:* The algorithms used in these steps follow directly from Peng and Wang^[29]. We
 498 implemented these steps using the R package “rqPen”^[30].

499 *Step 3:* Obtain

$$\hat{\beta} = \arg \min_{\|\beta\|_2=1} Q_3(\beta \mid \lambda_3, \hat{\gamma}^{(2)}),$$

500 where

$$Q_3(\beta \mid \lambda_3, \hat{\gamma}) = \sum_{i=1}^n \rho_{\tau} \left(Y_i - \sum_{k=0}^p [\hat{\gamma}_{k1} + \bar{B}(\mathbf{X}\beta) \hat{\gamma}_{k*}] G_{ik} \right) + n \sum_{d=2}^q p_{\lambda_3}(|\beta_d|).$$

501 Since $\bar{B}(\mathbf{X}\beta)$ is not linear in β , we adopt a first-order Taylor approximation. Let $\tilde{\beta}$ denote
 502 the current estimate of β . Then

$$\bar{B}(\mathbf{X}\beta) \hat{\gamma}_{k*} \mathbf{G}_k \approx \bar{B}(\mathbf{X}\tilde{\beta}) \hat{\gamma}_{k*} \mathbf{G}_k + \bar{B}'(\mathbf{X}\tilde{\beta}) \hat{\gamma}_{k*} \mathbf{X} \mathbf{G}_k (\beta - \tilde{\beta}).$$

503 For each component β_d , $d = 1, \dots, q$, we approximate

$$\bar{B}(\mathbf{X}\beta) \hat{\gamma}_{k*} \mathbf{G}_k \approx \bar{B}(\mathbf{X}\tilde{\beta}) \hat{\gamma}_{k*} \mathbf{G}_k + \bar{B}'(\mathbf{X}\tilde{\beta}) \hat{\gamma}_{k*} \mathbf{X}_d \mathbf{G}_k (\beta_d - \tilde{\beta}_d).$$

504 Therefore, $\hat{\beta}_d$ can be obtained by minimizing

$$Q_d = \sum_{i=1}^n \rho_{\tau}(Y_{di}^* - X_{di}^* \beta_d) + n p_{\lambda_3}(|\beta_d|),$$

505 where

$$\mathbf{Y}_d^* = \mathbf{Y} - \sum_{k=0}^p \left[\hat{\gamma}_{k1} \mathbf{G}_k + \bar{B}(\mathbf{X}\tilde{\beta}) \hat{\gamma}_{k*} \mathbf{G}_k - \bar{B}'(\mathbf{X}\tilde{\beta}) \hat{\gamma}_{k*} \mathbf{G}_k \mathbf{X}_d \tilde{\beta}_d \right],$$

506 and

$$\mathbf{X}_d^* = \sum_{k=0}^p \bar{B}'(\mathbf{X}\tilde{\beta}) \hat{\gamma}_{k*} \mathbf{G}_k \mathbf{X}_d.$$

507 The MCP-penalized estimator $\hat{\beta}^* = (\beta_1^*, \dots, \beta_q^*)^T$ is obtained as follows:

508 (1) For a given initial value $\tilde{\beta}$, compute $\mathbf{Y}_d^*$ and $\mathbf{X}_d^*$ according to the above expressions.

(2) Obtain $\hat{\beta}^*$ by applying an iterative coordinate descent algorithm for penalized quantile regression.

(3) Standardize $\hat{\beta}^*$ via

$$\hat{\beta} = \text{sign}(\hat{\beta}_1^*) \frac{\hat{\beta}^*}{\|\hat{\beta}^*\|_2}.$$

(4) Repeat steps (1)–(3) until convergence.

B Algorithm for the null model

Consider the intercept-only model

$$Y = m_0(\mathbf{X}\beta) + \epsilon.$$

We propose the following iterative algorithm for parameter estimation.

(0) Approximate $m_0(\mathbf{X}\beta)$ using B-spline basis functions:

$$m_0(\mathbf{X}\beta) \approx \gamma_{01} + \bar{\mathbf{B}}(\mathbf{X}\beta)\gamma_{0*}.$$

(1) For a given initial value $\hat{\beta}$, estimate $\hat{\gamma}_{01}$ and $\hat{\gamma}_{0*}$ using the “rq” function in R (package “quantreg”), where $\bar{\mathbf{B}}(\mathbf{X}\hat{\beta})$ serves as the design matrix.

(2) Update β by minimizing

$$\sum_{i=1}^n \rho_{\tau}(Y_i - \hat{\gamma}_{01} - \bar{\mathbf{B}}(\mathbf{X}\beta)\hat{\gamma}_{0*}),$$

using the linear approximation method described above.

(3) Replace $\hat{\beta}$ with the updated value and iterate steps (1) and (2) until convergence.

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